



Supplement of

Design and Modelling of a Cable-Driven Parallel-Series Hybrid Variable Stiffness Joint Mechanism for Robotics

Cihat Bora Yigit and Pinar Boyraz

Correspondence to: Cihat Bora Yigit (yigitci@itu.edu.tr) and Pinar Boyraz (pboyraz@itu.edu.tr)

- ms-8-65-2017-supplement-title-page.pdf
- Supplement Video.avi

The copyright of individual parts of the supplement might differ from the CC-BY 3.0 licence.